



# **Internet of Things Laboratory**

## **November 9th 2015**

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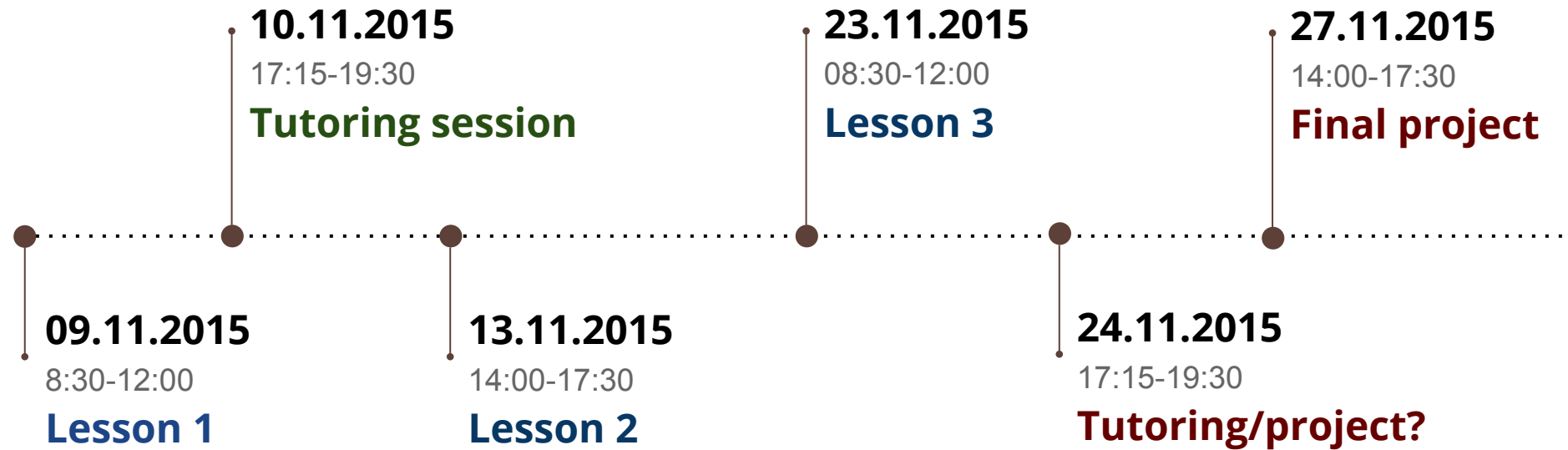


# Contacts

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- SENSES lab
  - <http://senseslab.di.uniroma1.it>



# Lessons Schedule





# Mailing list

- Subscribe to the course mailing list:  
[iot-laboratory-diuniroma1@googlegroups.com](mailto:iot-laboratory-diuniroma1@googlegroups.com)
- Slides and supporting material will be made available online at:  
<http://wwwusers.di.uniroma1.it/~spenza/lab2015.html>
- All lectures will be active learning sessions with lab exercises.

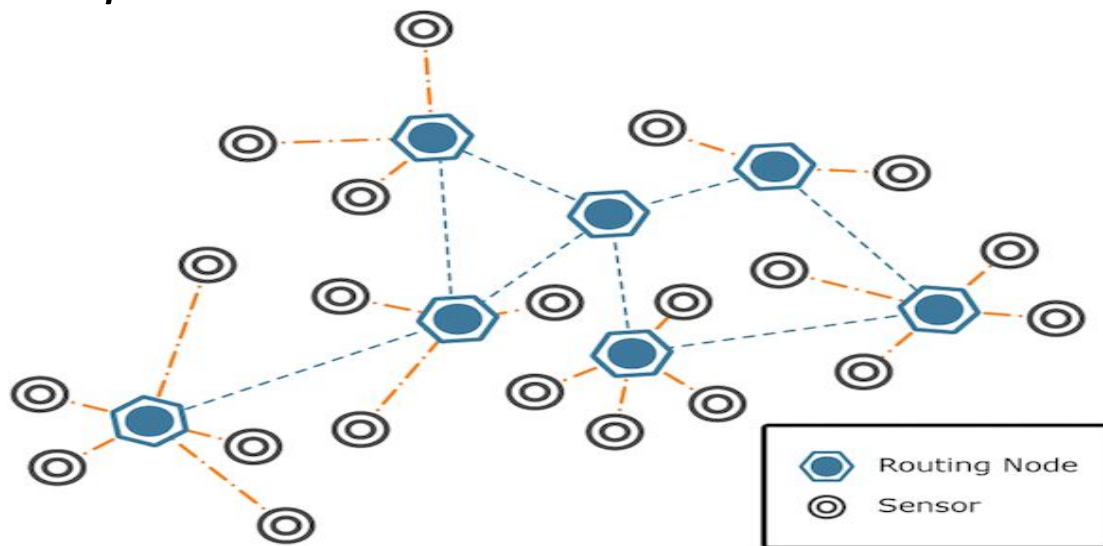


# Overview

- Introduction on Wireless Sensor Networks
- WSNs Projects of the SENSES lab
- Applications on Wireless Sensor Networks
- TinyOS introduction
- NesC programming language
- A simple application: Blink

# Introduction: Wireless Sensor Networks

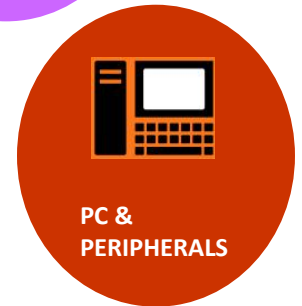
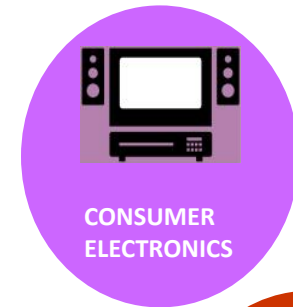
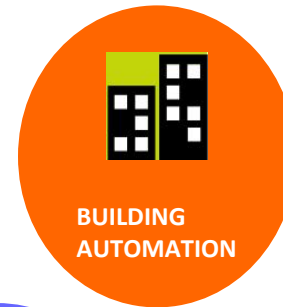
- *Network of small wireless sensor devices (nodes/motes), deployed in an ad-hoc fashion to cooperate on sensing a physical or environmental phenomenon.*



- Wireless communication medium
- Traffic is forwarded through several hops from source to sink node
- Power limited

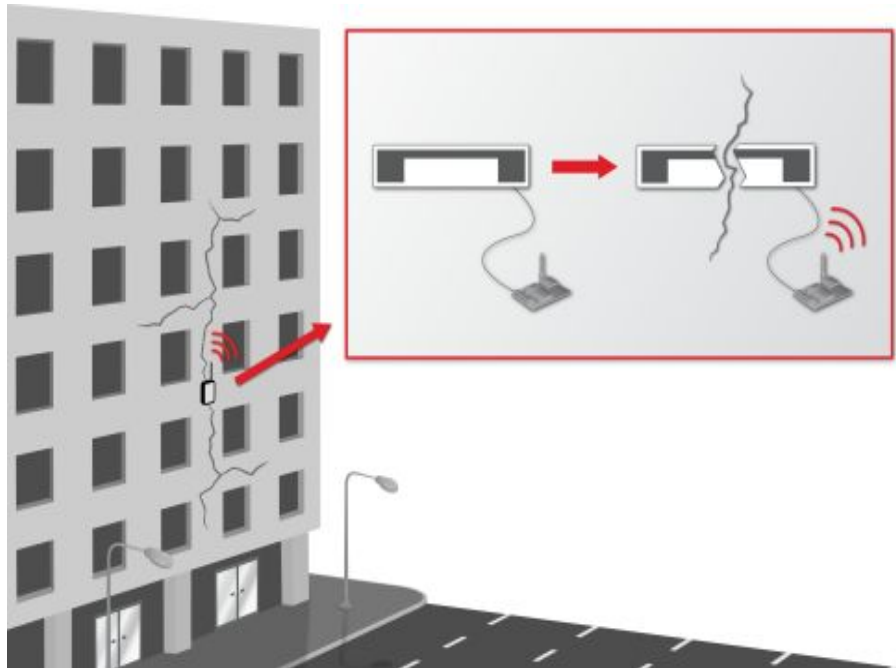
# Application Scenarios

- Environmental monitoring
  - fire/flood detection
- Monitoring of cultural heritage
  - “health” status of artworks
- Structural monitoring
  - integrity
  - life signs
- Medical
  - patient’s health status
- Military
  - surveillance
- Home automation
- Etc..



# Structural Health Monitoring

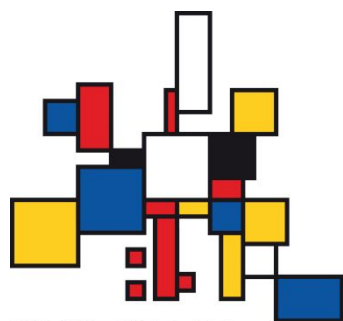
- Construction sites: inclinometers, pressure, displacement, ...
- Bridges, buildings: vibrating-wire strain gauges, displacement, ...





# Cultural Heritage Preservation

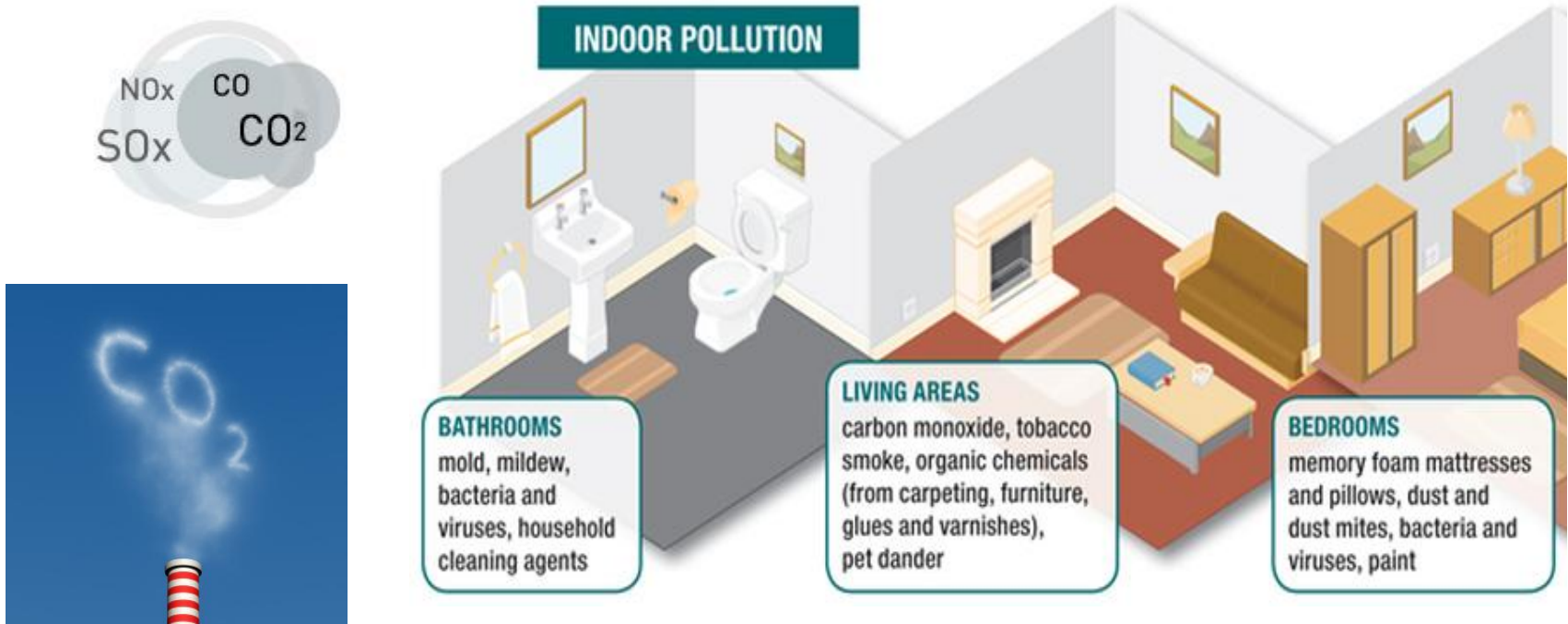
- Indoor/outdoor preservation: temperature, humidity, dust...
- Artworks monitoring during transportation and packing



**CULTURAL  
HERITAGE**  
A CHALLENGE  
FOR EUROPE

# Environmental Monitoring

- Outdoor air pollution: carbon monoxide, temperature, humidity,...
- Indoor air quality: CO<sub>2</sub>, carbon monoxide, dust level, humidity...
- Gas detection: methane, carbon monoxide,...



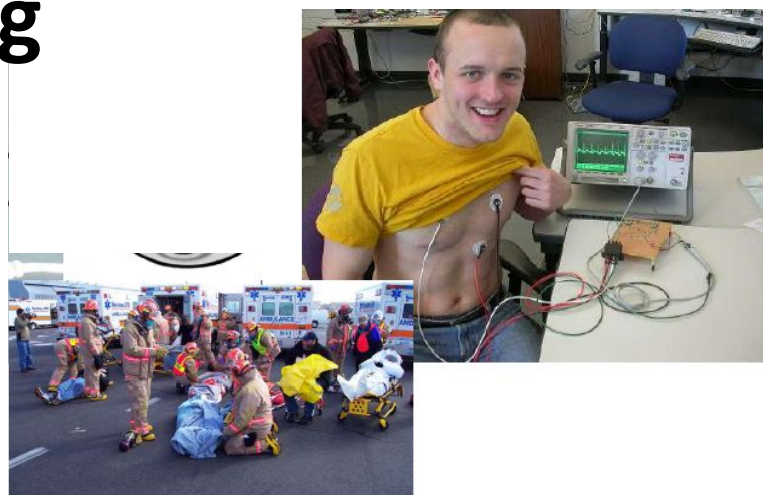
# Habitat Monitoring

- **Great Duck Island Project**
  - 150 Sensing nodes
  - Temperature, pressure, humidity
  - Data available on the Internet through a satellite link



# Healthcare, Assisted Living

- Vital sign monitoring
- Accident recognition
- Monitoring the elderly
- Data collection
- **Example: Intel**
  - 130 sensor nodes
  - Monitor the activity of elderly patients
  - Data is acquired with a wearable sensing nodes



# Domotic

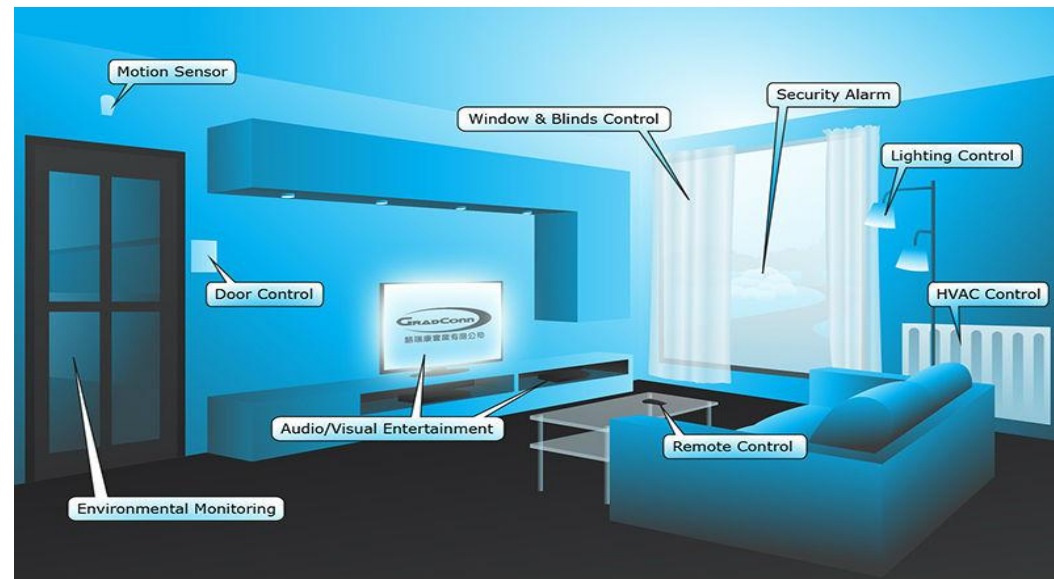
## Local and remote management of house

- Automation of appliances
- Brightness
  - Wireless switches
  - Window and blinds control
- Temperature
  - Wireless thermostats



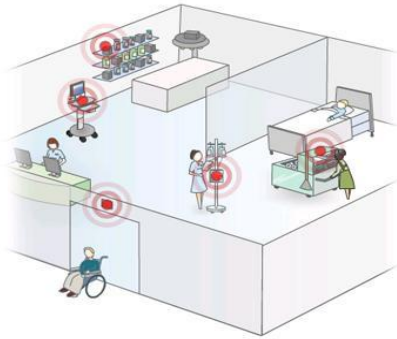
## House Control

- Door control
- Security alarm



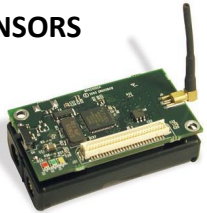
# CHIRON project

*Aim: person-centric health management*

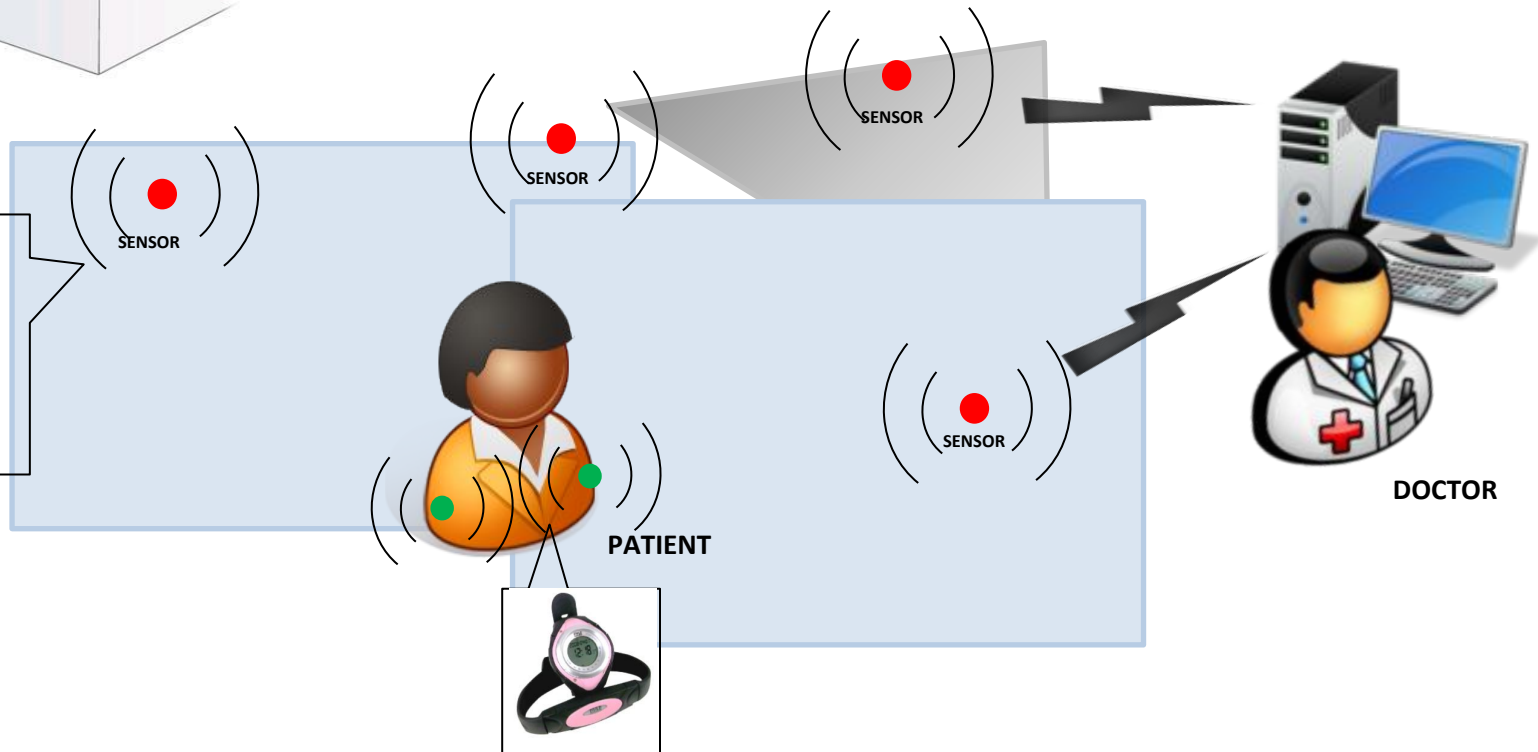


- Correlation between the health status of patients and the environmental conditions

ENVIRONMENTAL  
SENSORS



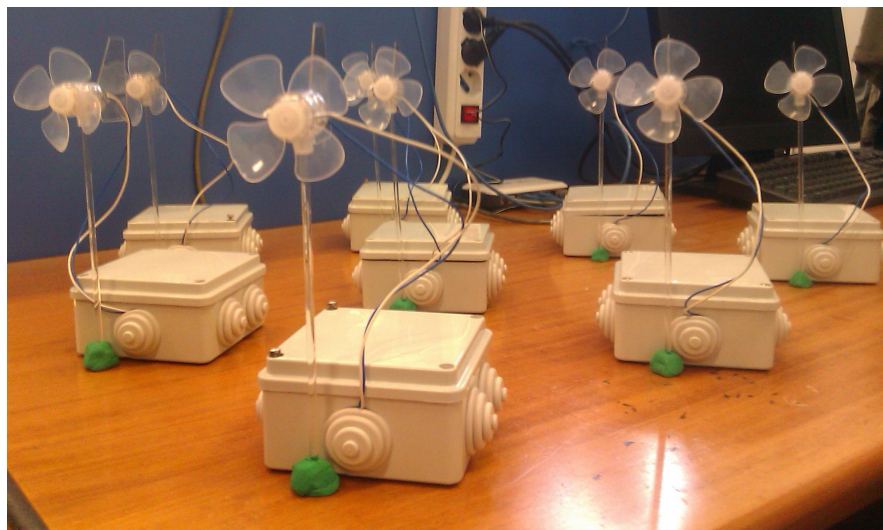
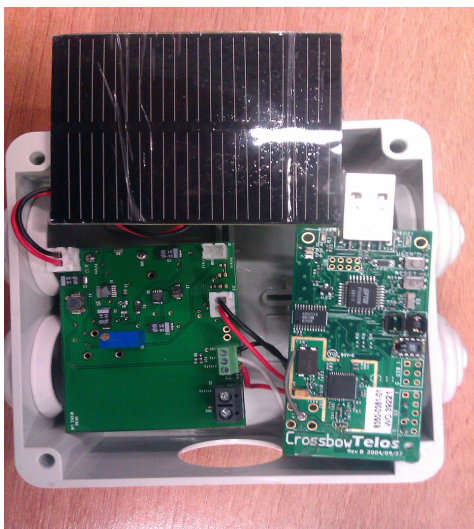
- Light
- Temperature
- Humidity
- Pollution



# GENESI project

*Aim: Long-lasting sensing systems for Structural Health Monitoring*

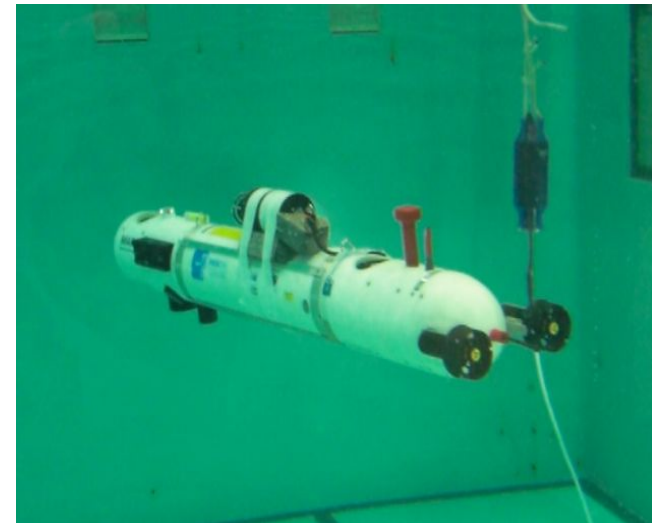
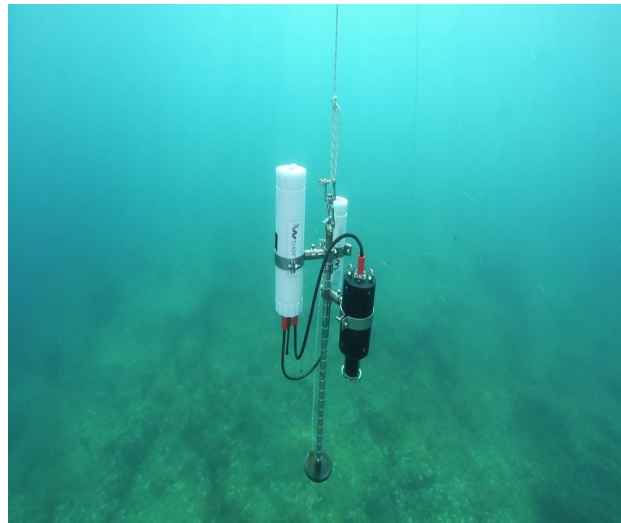
- Green wireless sensor networks equipped with energy harvesting and triggering capabilities
- Use of energy from renewable resources to extend the network lifetime



# SUNRISE project

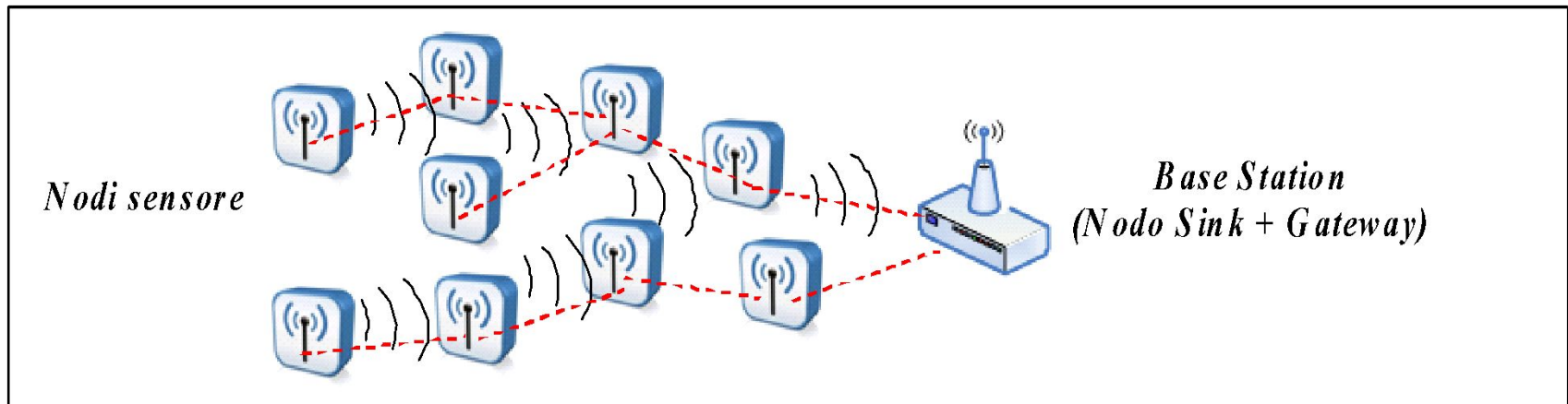
*Aim: Internet of Underwater Things*

- Sensing, monitoring, and actuating of the underwater communication networks
- Monitoring of oil, gas, CO2
- Prevention of natural disasters
- Chemical composition seabeds





# WSN Architecture



- Autonomous devices (*sensor nodes*) geographically distributed
- Equipped with sensors
- Collaborate to monitor the surrounding environment
- Key elements
  - Sensor Node (*node, mote*) and *Base Station*
  - Short-range *wireless* communication (*multi-hop*)

# WSN Characteristics

- Autoconfiguration
  - Manual configuration just not an option
- Scalability
  - Support large number of nodes
- Programmability
  - Re-programming of nodes in the field might be necessary, improves flexibility

# WSN Characteristics

- *Low cost*
  - Number of nodes in WSNs is high; to make deployments possible, the nodes should be extremely low cost
- *Energy efficient*
  - Both form communication and computation, sensing, actuating

# Design Aspects

- **System model**
  - Physical nodes vs. Functional components
  - Local computation vs. Communication
- **Hardware architecture of nodes**
  - Microprocessor/Microcontroller
    - IBM 8051, Atmel ATmega128L, XScale PXA271, TI MSP430,...
  - Chipset for communication and the related antenna
    - ChipCon CC1100 and CC2420
  - Bus of local communication
    - SPI, I2C

# Design Aspects

- **Communcation Protocols**
  - Diverse and heterogeneous protocols
  - Lower levels rely on standard protocols
    - IEEE 802.15.4, 6lowpan, Bluetooth, etc..
- **Routing algorithms**
  - Specific SPIN (Sensor Protocols for Information via Negotiation)
  - Directed Diffusion
  - Rumor Routing
  - Q-RC (Q-learning Routing and Compression)
  - etc..



# Energy Saving Solutions

- **Nodes**

- Design components and architecture hw/sw
- Mechanisms for (auto) power management

- **Network**

- *Energy-aware* protocols

- **System**

- *Energy-aware* applications



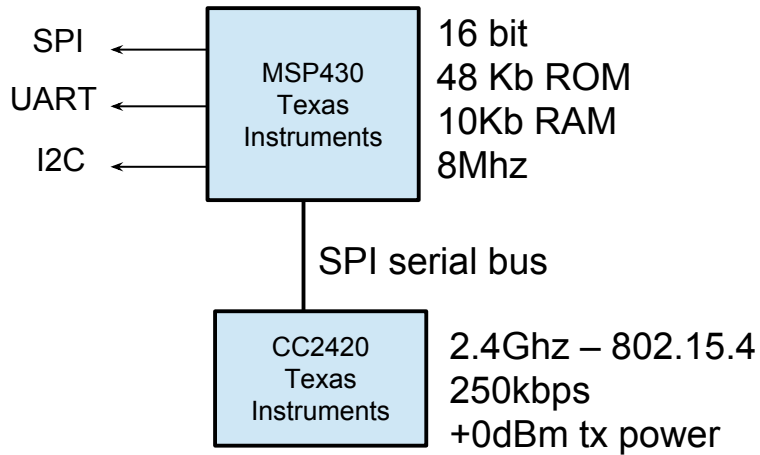
# Security Solutions

- **Nodes**
  - Encryption algorithms
  - Network
  - Cryptographic systems
  - Intrusion Detection & Monitoring Systems
- **System**
  - Cryptographic systems

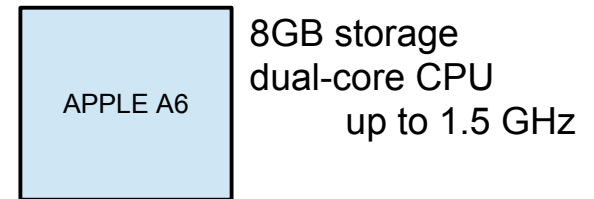
# Hardware Characteristics



TelosB



iPhone 5c





# Energy Consumption



## iPhone 5C

- Power: Non-removable Li-Po
- Expensive!
- Battery lasts < 1 day



## TelosB

- Power: 2xAA alkaline batteries
- Cheap!

# TinyOS



## ● *What is TinyOS?*

- A simple operating system for sensor networks and embedded systems
- Programming language is a C extension with extra features
- Open source →
  - Source code easily reusable
  - Large developers community
- Support for a great variety of hardware modules

## ● *Why a new Operating System?*

- Event-driven architecture; measure real-world phenomena
- Resource constraints; **Hurry up and sleep!**
- Hardware drivers, libraries, tools, compiler
- Modular

# TinyOS installation

**Quickest option:** install TinyOS via a virtual machine (VM)

1) Download and install VirtualBox

- <https://www.virtualbox.org>

2) Download, untar and install TinyOS installation on the VM

- [https://mega.nz/#!ekQSHKaR!  
Z2\\_gKHnyNIIh5XhvdCxpail2LgcHM-FKdLWqQ1QSvZ0](https://mega.nz/#!ekQSHKaR!Z2_gKHnyNIIh5XhvdCxpail2LgcHM-FKdLWqQ1QSvZ0)

3) Right click on the VirtualBox icon, and then Open

4) Last step is setting up the usb device on your VM

- Devices->USB Devices-> XBOW Crossbow TelosRevB



# TinyOS Installation

## Alternative options

- **TinyOS 2.1.2 installation**
  - [http://tinyos.stanford.edu/tinyos-wiki/index.php/Installing\\_TinyOS#Officially\\_Supported\\_Methods](http://tinyos.stanford.edu/tinyos-wiki/index.php/Installing_TinyOS#Officially_Supported_Methods)
  - [http://tinyos.stanford.edu/tinyos-wiki/index.php/TinyOS\\_Tutorials](http://tinyos.stanford.edu/tinyos-wiki/index.php/TinyOS_Tutorials)
- **Linux:** .rpm and .deb packages for Fedora and Ubuntu
  - **Recommend debian system installation on Ubuntu**
- **Windows:** .rpm pkg, uses Cygwin to emulate Linux software layer
- **OS X:** Unofficially supported
  - [http://tinyos.stanford.edu/tinyos-wiki/index.php/Installing\\_tinyos-2.x\\_on\\_Mac\\_OS\\_X\\_\(Tiger\\_%26\\_Leopard\)](http://tinyos.stanford.edu/tinyos-wiki/index.php/Installing_tinyos-2.x_on_Mac_OS_X_(Tiger_%26_Leopard))
  - <https://olafland.wordpress.com/2012/06/25/tinyos-on-mac-os-x-10-7-lion/>

# TinyOS

- A library that includes nesC components and offers several functions like a common operating system:
  - **Scheduler**
  - **Driver**
    - Components for sensor data reading
    - Components for sending commands to actuators
    - Components for controlling radio communication
  - **Power Management**
    - Maintain available HW in the lowest possible power level
- **No kernel concepts, processes, memory management**

# Native support for low-power operation

- Microcontroller Power Management
  - Microcontrollers should always be in the lowest power state possible
  - TinyOS handles state transitions automatically to achieve maximum power saving
- Radio Power Management
  - Duty-cycle radio to save energy and extend network lifetime
- Peripheral Energy Management
  - Energy-efficient scheduling of sensing operation and peripheral access

# TinyOS

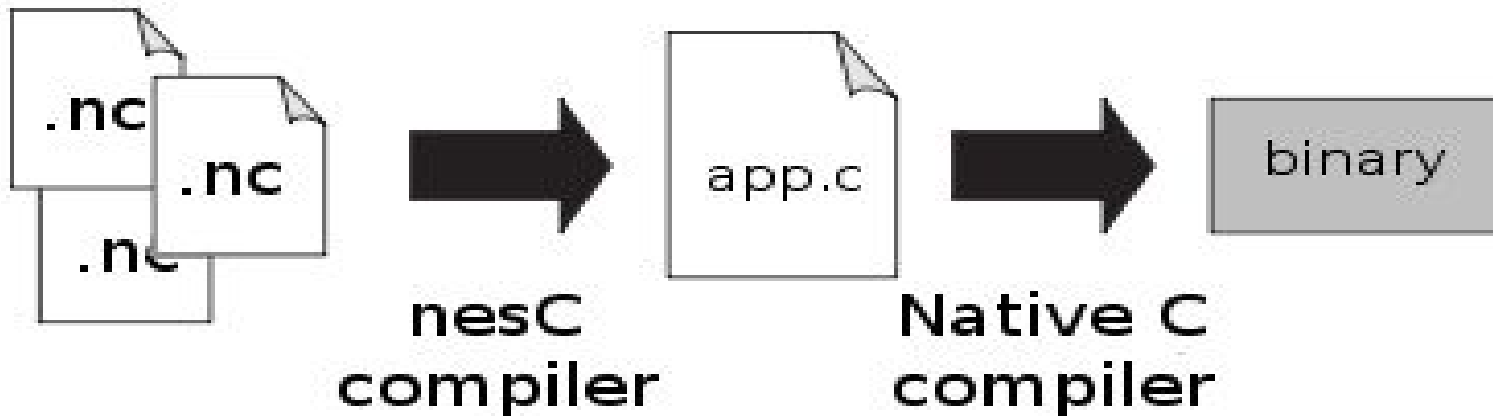
- For each application there is the *top-level* configuration that includes the *MainC* component
  - Provides services based on TinyOS ( $\approx$  200 Bytes)

```
configuration BlinkAppC
{
}
implementation
{
  components MainC, BlinkC, LedsC;
  ...

  BlinkC -> MainC.Boot;
  ...
  BlinkC.Timer0 -> Timer0;
  ...
  BlinkC.Leds -> LedsC;
}
```

# TinyOS-compiling

- TinyOS includes *Makefiles* to support the build process
- Create a *Makefile* in your application directory
  - COMPONENT = [MainComponentAppC] # the name of your AppC file







# TinyOS-make system

- To compile an application without installing on a mote, run in the application directory:
  - `make [platform] #ex. telosb`
- To compile an application, and install it on a mote
  - `make [platform] [re]install,[node ID] [programmingBoard,address]`
  - node ID: 0-255, for radio transmissions
  - platform: defined in `$TOOSROOT/tos/platforms`
  - Programming board: for telosb use: `bsl`
  - Address: as reported by motelist
    - ex. `/dev/ttyUSB0`



# TinyOS commands

- **motelist**
  - list of motes physically connected to your pc
- **make telosb**
  - compile your code for the telosb mote
- **make clean**
  - clean up all the compiled binary files
- **make telosb install,id bsl,address**
  - compile your code for telosb, install it on a mote, give it a network id
  - example: `make telosb install,0 bsl,/dev/ttyUSB0`
- **make telosb reinstall,id bsl,address**
  - use existing runnable, install in on telosb, give it a network id



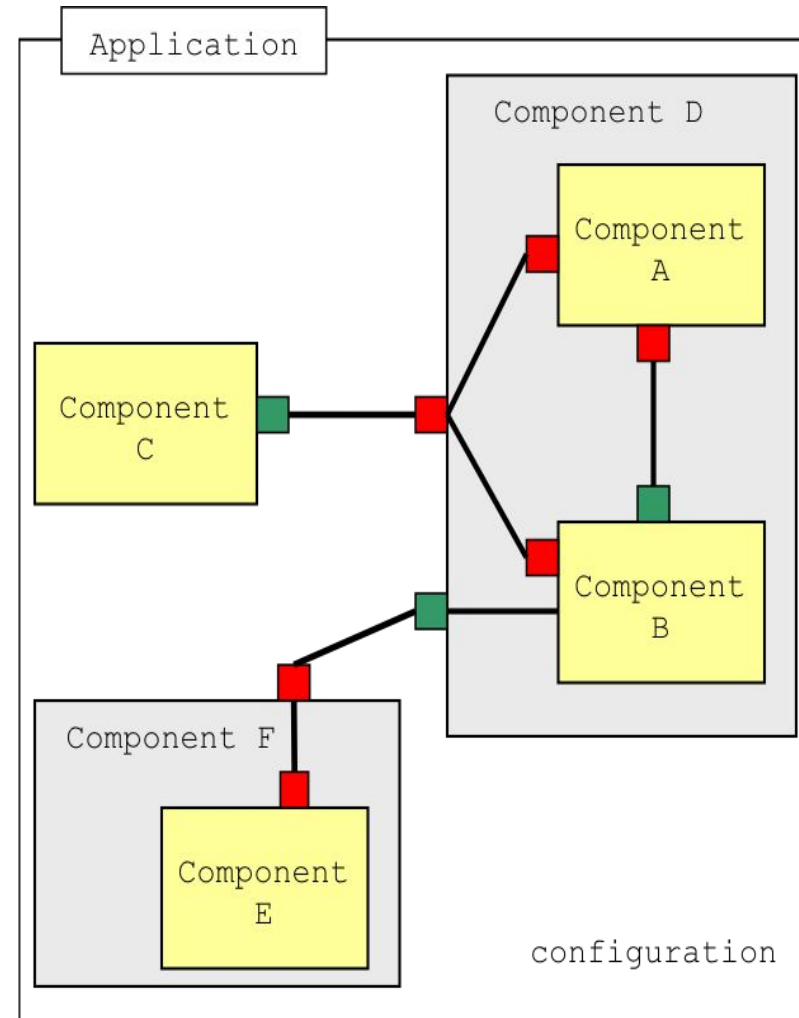
# nesC Programming Language

*How do we program wireless sensor devices*

- **nesC**
  - **Reference manual**  
<http://nesc.sourceforge.net/papers/nesc-ref.pdf>
- C extension language for networked embedded systems
- **Static language:**
  - no dynamic memory allocation
  - all resources known at compile-time

# nesC Programming Language

- **Application:** one or more *components* are connected to each other (*wired*) to form an executable
- **Components:**
  - *Modules:* provide application code, implementing *interfaces*
  - *Configurations:* wire interfaces used by components to interfaces provided by others
- **Interfaces:** access to components
  - *uses*
  - *provides*



# nesC Modules

- Provide/use one or more interfaces

```
module XYZ1
{
  provides interface Interfacel as I1;
  provides interface Interface2;
  ...
  uses interface Interface3 as I3;
  uses interface Interface2;
  ...
}
implementation
{
  command void I1.cmd1() {
    ...
  }

  event void Interface2.ev1() {
    ...
  }
}
```

# nesC Configurations

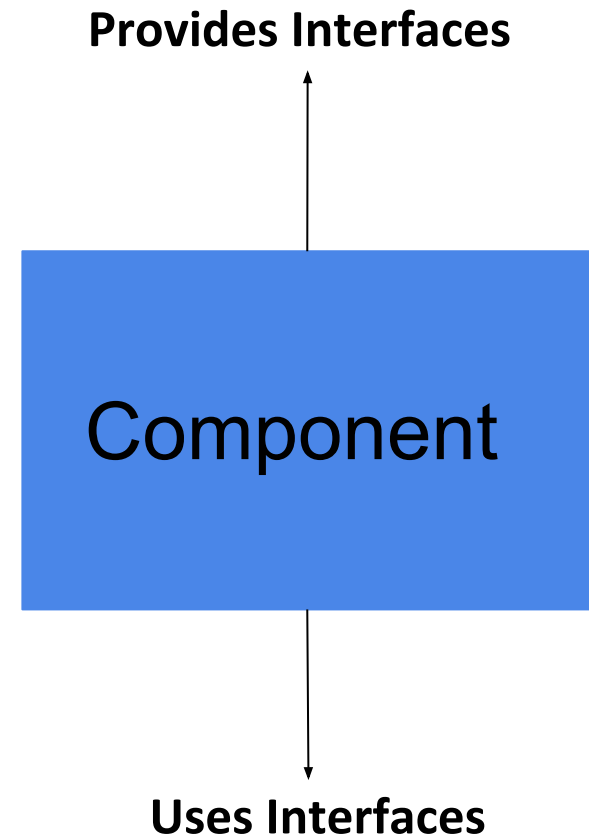
- Two components are linked together by *wiring* them
- Interfaces on user component are wired to the same interface on the provider component

```
configuration XYZ
{
  ...
}
implementation
{
  components XYZ1, XYZ2;

  ...
  XYZ1.Interface1 -> XYZ2.Interface1;
  XYZ1.Interface2 -> XYZ2;
  ...
}
```

# nesC Interfaces

- **Commands:** functions to be implemented by the interface of the provider; how to use the interface
- **Events:** functions to be implemented by the interface of the user



# nesC Concurrency

Two computational  
abstractions

Asynchronous events

Tasks

- can run preemptively (async)
- interrupt handlers
- race conditions!

- schedule a function to be called later
- run in a single execution context
- no preemption!
- FIFO





# nesC Tasks

- Run sequential and to completion
- Do not preempt

```
task void computeTask() {
    uint32_t i;
    for (i = 0; i < 10001; i++) {}
}

event void Timer0.fired() {
    post computeTask();
    call Leds.led0Toggle();
}
```



# nesC Events

- Run to completion; may preempt tasks and event
- Origin: hardware interrupts/split-phase completion

```
event void Boot.booted() {
    call Timer0.startPeriodic(250);
}
event void Timer0.fired() {
    post computeTask();
    call Leds.led0Toggle();
}
```

# nesC Split-phase

- Enable TinyOS components to easily start several operations at once and have them executed in parallel.

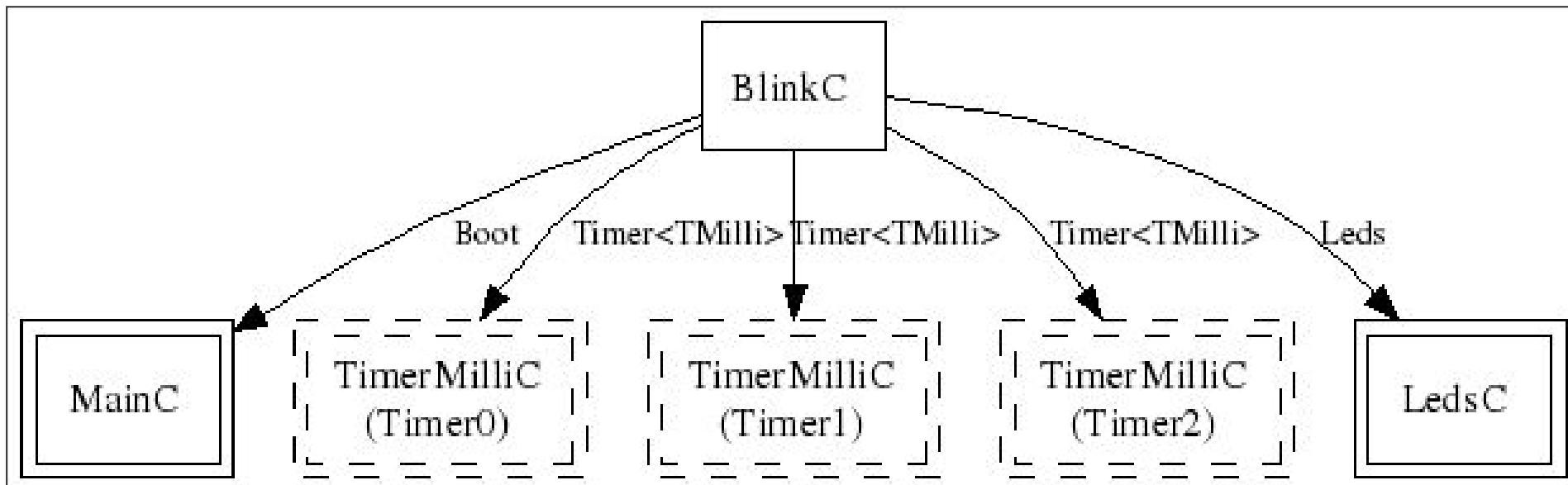
| Blocking  | Split-Phase  |
|---|--|
| <pre>state = WAITING; op1 ();  sleep (500);  op2 (); state = RUNNING;</pre> | <pre>state = WAITING; op1 ();  call Timer.startOneShot (500);  event void Timer.fired() {     op2 ();     state = RUNNING; }</pre> |

# Example: Blink Application

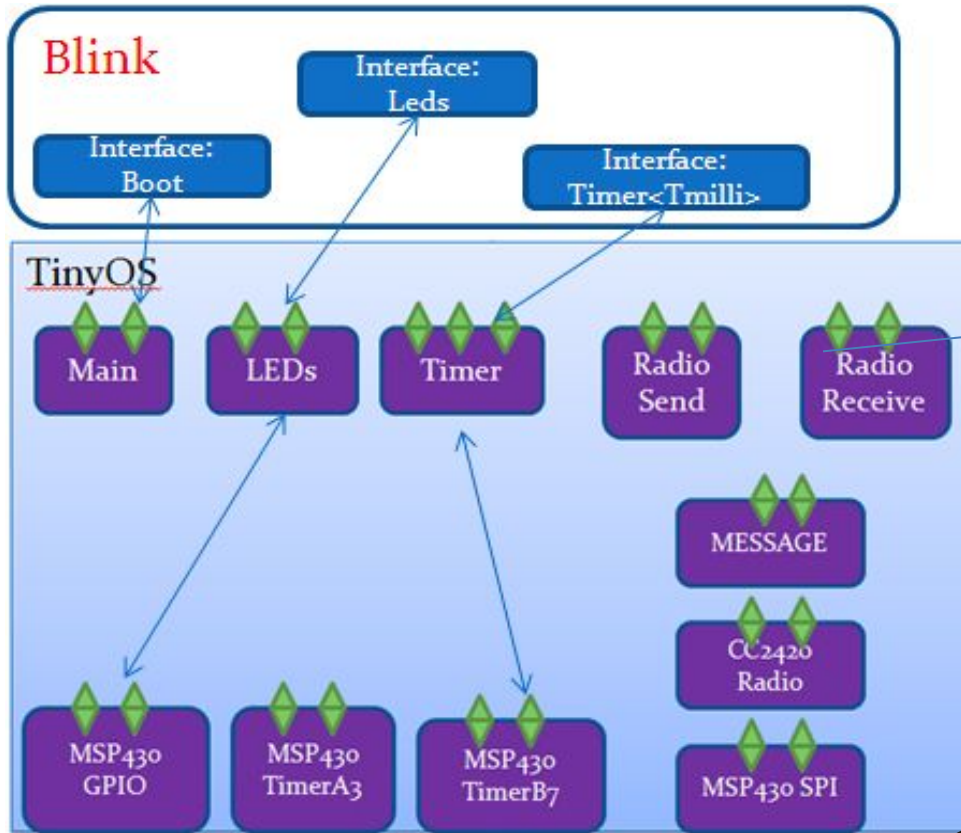
- `/apps/Blink` in the TinyOS tree
- Causes three LEDs to turn on and off
  - The LEDs turn on and off at the frequencies 1Hz, 2Hz, and 4Hz
- Application components
  - *BlinkAppC (Configuration)*
  - *BlinkC (Module)*
- System Components
  - *MainC, LedsC, TimerMilliC*

# BlinkApp Components

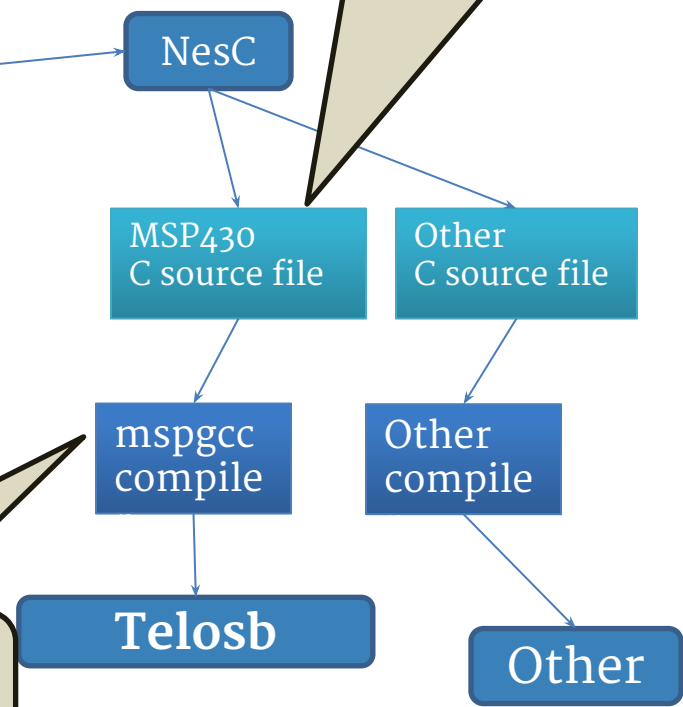
- **BlinkAppC**: Component graph
  - Single box: module, double box: configuration
  - Dashed lines: generic component



# Blink Compilation



nesC compiler composes the necessary components and produces a platform specific C source file



Uses a native GNU C compiler for specific microcontroller and load code onto the platform.



# BlinkAppC.nc

```
configuration BlinkAppC
{
}
implementation
{
    components MainC, BlinkC, LedsC;
    components new TimerMilliC() as Timer0;
    components new TimerMilliC() as Timer1;
    components new TimerMilliC() as Timer2;

    BlinkC -> MainC.Boot;

    BlinkC.Timer0 -> Timer0;
    BlinkC.Timer1 -> Timer1;
    BlinkC.Timer2 -> Timer2;
    BlinkC.Leds -> LedsC;
}
```



# BlinkC.nc

```
#include "Timer.h"

module BlinkC
{
  uses interface Timer<TMilli> as Timer0;
  uses interface Timer<TMilli> as Timer1;
  uses interface Timer<TMilli> as Timer2;
  uses interface Leds;
  uses interface Boot;
}
implementation
{
```





# BlinkC.nc

```
event void Boot.booted()  
{  
    call Timer0.startPeriodic( 250 );  
    call Timer1.startPeriodic( 500 );  
    call Timer2.startPeriodic( 1000 );  
}
```

# Example: Blink Timer

- *BlinkC.nc*

```
event void Timer0.fired()
{
    dbg("BlinkC", "Timer 0 fired @ %s.\n", sim_time_string());
    call Leds.led0Toggle();
}

event void Timer1.fired()
{
    dbg("BlinkC", "Timer 1 fired @ %s \n", sim_time_string());
    call Leds.led1Toggle();
}

event void Timer2.fired()
{
    dbg("BlinkC", "Timer 2 fired @ %s.\n", sim_time_string());
    call Leds.led2Toggle();
}
}
```



# Exercise

Modify the Blink application

- Use only one timer firing once per second
- When the timer fires, increment a counter
- Display the value of the counter using the LEDs



# Example: Blink Counter

- *BlinkC.nc*

```
uint8_t counter = 0;  
  
event void Boot.booted()  
{  
    call Timer0.startPeriodic( 1024 );  
}
```

|          | 8 bits  | 16 bits  | 32 bits  | 64 bits  |
|----------|---------|----------|----------|----------|
| signed   | int8_t  | int16_t  | int32_t  | int64_t  |
| unsigned | vint8_t | vint16_t | vint32_t | vint64_t |



# Example: Blink Counter

- *BlinkC.nc*

```
event void Timer0.fired()
{
    counter++;
    if (counter & 0x1) {
        call Leds.led0On();
    }
    else {
        call Leds.led0Off();
    }
    if (counter & 0x2) {
        call Leds.led1On();
    }
    else {
        call Leds.led1Off();
    }
    if (counter & 0x4) {
        call Leds.led2On();
    }
    else {
        call Leds.led2Off();
    }
}
```